

## AN ILLUSTRATIVE GUIDE

Design \& Fabrication for a Partial Foot Prosthesis that will...

- Reduce Friction
- Reduce Shearing
- Reduce Pressure
- Restore Propulsion
- Restore Limb Length
- Preserve Residual Limb


## Introduction

This book is in response to requests from practitioners interested in a comprehensive prosthetic program to manage partial foot amputations.

## Reimbursement Codes

Any reference to reimbursement codes are based on suggestions from practitioners using these techniques and are not suggested by Allard USA or validated by any reimbursement agency.

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## Applicable Amputation Levels

The concepts in this book apply to any partial foot amputation first ray or shorter.


Metatarsophalangeal (MTP)



Transmetatarsal (TMT)


Transtarsal (Chopart)

## PARTIAL FOOT CHALLENGES

## I. Loss of Propulsion



Plantar Fascia Stretches


Without the first ray windlass mechanism, the foot is considered "apropulsive"


Normally calf group muscle strength is balanced by foot lever arm length.

With amputation, muscles overpower the shortened lever arm, shearing connective tissue creating calluses.

## OPTIONS

Foot Prosthesis or Short AFO


A foot prosthesis or short AFO with filler prosthesis cannot replace the lost propulsive lever arm.

## Carbon Fiber Footplate



A carbon fiber footplate can only partially lengthen the propulsive lever arm, still allowing shearing leading to callus formation.

Immobilization


Immobilization can't help restore the propulsive lever arm and is proven to induce disuse atrophy.

## Carbon Fiber Footplate WITH a Lateral Strut



A footplate with a lateral strut leading into a tibial tubercle height pretibial shell can minimize or eliminate shearing forces by augmenting the shortened lever arm.

## RESIDUAL FOOT PRESERVATION

## Managing Friction



Friction can be managed by making sure the socket isn't too large and shoes aren't too big.

Managing Pressure


Pressure can be managed by making sure the socket isn't too small or shoes aren't too tight.


## Residual Foot Preservation



## Foot Preservation Summary

To optimize residual foot soft tissue integrity it is important to make sure it is protected from:

- Friction
- Pressure
- Shearing forces

Studies have shown destructive forces are distal to the residuum using BlueROCKER ${ }^{\circledR}$, thereby preserving the residual foot.

Range of Motion


Nominal ROM at the ankle is $20^{\circ}$ dorsiflexion and $40^{\circ}$ plantarflexion.

Calcaneal Angle


With the ankle at neutral, the normal calcaneal angle is $40^{\circ}$.

TMA


At TMA level amputation, expect 3/8 to $1 / 2^{\prime \prime}$ acquired limb length deficit.


At Lisfranc level, expect I/2 to 5/8" acquired limb length deficit.

CHOPART


At Chopart level, expect 7/8 to | 3/8" acquired LLD. Note acquired bulbous heel associated with ankle plantarflexion.

## Determine leg length discrepancy



Measure limb length from fibular head to floor on both involved and uninvolved sides to determine acquired LLD.


Determine if restoring calcaneal angle can resolve LLD. Have patient stand on end of IX4 board and lift the other end. Note/document calcaneal angle.

Adjust for leg length discrepancy


Wedge anterior aspect of calcaneous to previous measurement. If LLD is not fully resolved, it will be necessary to post the heel section of the socket. See page 8, step 5 for illustration.


## Restore Propulsion



Tibial tubercle height pre-tibial shell, lateral strut and kinetic return footplate help restore propulsion.

Data show that at TMA level, the ankle loses 85\% of propulsive power. At Lisfranc and Chopart, the loss is $100 \%$ due to lack of a propulsive lever arm.

Compensations include hip-hiking, trunk lean, shorter sound side step length, and increased trunk torsion to advance the involved side limb through space.

Management of any partial foot amputation requires restoration of the propulsive lever arm.

## PROSTHESIS FABRICATION

## I. Cast



Cast residual foot. Also cast contralateral foot so the prosthesis can be built to match.

## 3. Distal Cushion



Mold I/8" Impression PuffTM (25 Durometer Shore A EVA) for distal cushion (L5668).

## 5. Post



Post anterior aspect of socket to restore ankle neutral, and post posterior aspect if there is any residual LLD (see page 6).
2. Positive Model


Make positive model of residual limb.

## 4. Mold Socket



Mold I/8" black co-polymer for the socket (included in base code L5020).

## 6.Trim Lines



Trim anterior aspect of socket at start of filler prosthesis. Trim posterior aspect as a foot orthosis.

## PROSTHESIS FABRICATION

## 7. Align to BlueROCKER



Align socket to BlueROCKER ${ }^{\circledR}$, trimming to accommodate lateral strut if necessary.

## 8. Laminate Layers of Microcell Puff ${ }^{\circledR}$

Laminate I/4" layers of Microcell Puff Lite to build the filler prosthesis, conforming it to the rocker footplate.

## 9. Shape Foot and Socket



Shape to match the length, width and sagittal plane profile of the contralateral foot.

IO. Add Interface


Line pretibial shell with SoftKIT, ComfortKIT, or Custom Interface to protect tibial crest.

## I I. Align Tibial Shell



Align pretibial shell to tibial crest for equal top to bottom pressure distribution before securing prosthesis to footplate.

## SHOE SELECTION \& EXERCISES

## Shoe Selection



Footwear requirements include adequate heel/toe height differential, and toe rocker sole. A well constructed shoe (firm counter and shank) will produce better results.
Flat-soled shoes (dress, court or deck shoes) are contraindicated.

## Exercises

These exercises will help the wearer acclimate to their new environment by learning to take advantage of the energy return properties of the prosthesis. The importance of doing these exercises prior to walking cannot be overstated.

## TRI-PLANAR LUNGES



Step out, step ahead and cross-step, making sure both knees are flexed.

BABY SQUATS


Baby squats (heels stay on the ground). Illustrated are sagittal, rotate right and rotate left squats.

## TRI-PLANAR HIP EXCURSION



Determine excursion distance frontal plane, and then rotating forward and rotating to the back.

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